

# 2026.1 GPT3 Registrar Out-of-Practice Education Program



**Region: Victoria**

**Subregion: Metro Rural South West**

Registrars must attend the RACGP's out-of-practice education program during their GPT3 term as a requirement to Fellow. Attendance contributes to their education hours within the registrar's TMS portfolio.

The GPT3 out-of-practice education program comprises a mix of large group and small group activities facilitated either face to face or via an online platform.

In 2026.1, GPT3s will attend two workshop days and a half day webinar, facilitated in the registrar's subregion.

An evening webinar program is facilitated at a Victoria-wide level.

- Registrars are required to attend six hours of the evening webinar program.
- Registrars can choose the sessions to attend based on own interest areas.

The out-of-practice education program is underpinned by the [RACGP Curriculum and syllabus](#).

**Registrars are required to attend 24 hours in their GPT3 term.**

**Please note:**

- The Program Support Officer for the South West region can be contacted at [vicmrsw.pso@racgp.org.au](mailto:vicmrsw.pso@racgp.org.au)
- Registrars will receive further details about each out-of-practice education event, prior to the date.
- The address for Prickly Moses (the core location for out-of-practice education events) is: 10 Hovey's Road Barongarook VIC 3429

Date	Time	Education Hours	Event	Registrar term	Type	Content	Location
Fri 20 March	9.00am - 5.00pm	8	Quality, Safety & Reflective Practice	GPT3	Large	Registrars will receive the program mid-March	Prickly Moses/Otway Estate (TBC)
Fri 8 May	9.00am - 5.00pm	8	Ethical and Sustainable Practice	GPT3	Large	Registrars will receive the program late April	Prickly Moses/Otway Estate (TBC)
Fri 31 July	9.00am - 1.00pm	4	Peer-led Small Group Learning (SGL) #1 Hot Topics	GPT3	Small	Registrars will receive the program late May	Online via Zoom
Prior to CoT	7.00am - 8.00pm	6	Evening webinars	GPT3	Large	Registrars will receive the program mid-February	Online via Zoom